

# Spectral Domain Analysis of an Open Slot Ring Resonator

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**Abstract**—A full wave analysis of an open slot ring resonator on a dielectric substrate is presented. It is based upon Galerkin's method in the Hankel transform domain. The computed resonant frequencies for several slot widths agree well with the experimental values on alumina substrate with  $\epsilon_r = 9.6$  in the 26–37-GHz frequency range.

## I. INTRODUCTION

MICROSTRIP DISK and ring resonators are utilized as resonators, filters, antennas, and other circuit elements for microwave integrated circuits [1]. These resonators early have been analyzed by a magnetic wall model [2]–[4]. Although this analysis method is simple and useful, more rigorous analyses have been required for more accurate design. Hence many improved analyses have been reported [5]–[7]. Furthermore, Araki and Itoh have developed a rigorous full wave analysis to obtain accurate resonant frequencies and radiation patterns [8]. The analysis is based upon Galerkin's method in the Hankel transform domain.

Meanwhile, the authors have developed slot ring resonators to measure accurate guide wave lengths of slot lines [9]. Although slot ring resonators are considered to be useful as circuit elements for microwave integrated circuits, they have not been analyzed yet.

This paper presents resonant frequencies of an open slot ring resonator determined by the Hankel transform domain analysis. In Section II, dyadic Green functions and the characteristic equation are derived and the sensitivity of the solution with respect to the basis functions is investigated. In Section III, the experimental procedure for alumina substrate is described. In Section IV, the computed resonant frequencies are compared with the measured values. It is shown that the numerical results agree well with the experimental results, especially for wide width region of slots.

## II. ANALYSIS METHOD

### A. Green Functions

Fig. 1 shows the slot ring resonator to be analyzed. A ring-like slot line is placed on the bottom surface of the substrate of thickness  $d$ . It is assumed that metals are infinitely thin and perfect conductors and that the sub-

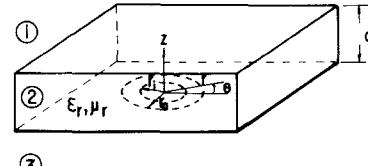


Fig. 1. Slot ring resonator and the coordinate system. ①Upper air region. ②Substrate region. ③Lower air region.

strate material, whose permittivity and permeability are  $\epsilon_r$  and  $\mu_r$ , respectively, is lossless.

1) *Field Expression*: The first step is to derive the tangential field components. It is well known that the electromagnetic fields can be obtained from a superposition of TE and TM fields.

The axial field components  $E_z(r, \theta, z)$  and  $H_z(r, \theta, z)$ , which satisfy the Helmholtz equation, can be expressed with the definition of the Hankel transform as follows [10].

#### A) In upper air region ( $z > d$ ):

$$E_{z1}(r, \theta, z) = e^{jn\theta} \int_0^\infty A^e(\alpha) e^{-j\beta_1(z-d)} J_n(\alpha r) \alpha d\alpha \quad (1a)$$

$$H_{z1}(r, \theta, z) = e^{jn\theta} \int_0^\infty A^h(\alpha) e^{-j\beta_1(z-d)} J_n(\alpha r) \alpha d\alpha. \quad (1b)$$

#### B) In substrate region ( $d > z > 0$ ):

$$E_{z2}(r, \theta, z) = e^{jn\theta} \int_0^\infty \{ B^e(\alpha) \sin(\beta_2 z) + C^e(\alpha) \cos(\beta_2 z) \} J_n(\alpha r) \alpha d\alpha \quad (1c)$$

$$H_{z2}(r, \theta, z) = e^{jn\theta} \int_0^\infty \{ B^h(\alpha) \sin(\beta_2 z) + C^h(\alpha) \cos(\beta_2 z) \} J_n(\alpha r) \alpha d\alpha. \quad (1d)$$

#### C) In lower air region ( $0 > z$ ):

$$E_{z3}(r, \theta, z) = e^{jn\theta} \int_0^\infty D^e(\alpha) e^{j\beta_3 z} J_n(\alpha r) \alpha d\alpha \quad (1e)$$

$$H_{z3}(r, \theta, z) = e^{jn\theta} \int_0^\infty D^h(\alpha) e^{j\beta_3 z} J_n(\alpha r) \alpha d\alpha \quad (1f)$$

where subscripts 1, 2, and 3 designate the upper air, substrate and lower air region, and

$$\beta_1^2 = \omega^2 \epsilon_1 \mu_1 - \alpha^2 \quad \beta_2^2 = \omega^2 \epsilon_2 \mu_2 - \alpha^2$$

$$\beta_3^2 = \omega^2 \epsilon_3 \mu_3 - \alpha^2$$

$$\epsilon_1 = \epsilon_3 = \epsilon_0 \quad \epsilon_2 = \epsilon_r \epsilon_0$$

$$\mu_1 = \mu_3 = \mu_0 \quad \mu_2 = \mu_r \mu_0$$

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where  $\alpha$  is the Hankel transform variable,  $\omega$  is the angular resonant frequency,  $\epsilon_0$  and  $\mu_0$  are the free space permittivity and permeability.  $J_n(\alpha r)$  is the Bessel function of the first kind and  $n$ th order.  $A^e(\alpha), \dots, D^h(\alpha)$  are unknown coefficients which are determined from the boundary conditions at the interfaces  $z=0$  and  $z=d$ . The radical and azimuthal field components derived from (1) contain the Bessel functions of  $n-1$ th order and  $n+1$ th order because of the derivative with respect to the argument  $r$ . Therefore, the following expressions will be used to reduce them to the same order of the Bessel functions:

$$E_{i\pm}(r, \theta, z) = E_{ri}(r, \theta, z) \pm jE_{\theta i}(r, \theta, z) \quad (2a)$$

$$H_{i\pm}(r, \theta, z) = H_{ri}(r, \theta, z) \pm jH_{\theta i}(r, \theta, z) \quad (2b)$$

where  $E_{ri}(r, \theta, z)$  and  $E_{\theta i}(r, \theta, z)$  are the radical and azimuthal electric field components, respectively, and  $H_{ri}(r, \theta, z)$  and  $H_{\theta i}(r, \theta, z)$  are the radical and azimuthal magnetic field components, respectively.

2) *Boundary Conditions*: The second step is to apply the boundary conditions at the interfaces  $z=0$  and  $z=d$  to obtain Green functions. They are as follows.

a) *Top substrate surface* ( $z=d$ ): The tangential field components are continuous

$$E_{1\pm}(r, \theta, d) = E_{2\pm}(r, \theta, z) \quad (3a)$$

$$H_{1\pm}(r, \theta, z) = H_{2\pm}(r, \theta, z). \quad (3b)$$

b) *Bottom substrate surface* ( $z=0$ ): The electric field components are continuous and the magnetic field components are related to the conductor current densities, that is,

$$E_{2\pm}(r, \theta, 0) = E_{3\pm}(r, \theta, 0) = E_{\pm}(r, \theta, 0) \quad (4a)$$

$$J_{\pm}(r, \theta, 0) = \pm j\{H_{2\pm}(r, \theta, 0) - H_{3\pm}(r, \theta, 0)\} \quad (4b)$$

where  $E_{\pm}(r, \theta, 0)$  and  $J_{\pm}(r, \theta, 0)$  are the unknown tangential electric field components and conductor current densities, respectively.

From (2), (3), and (4a),  $B^e(\alpha)$ ,  $C^e(\alpha)$ ,  $D^e(\alpha)$ ,  $B^h(\alpha)$ ,  $C^h(\alpha)$ , and  $D^h(\alpha)$  are expressed in terms of the tangential electric field components  $E_{\pm}(r, \theta, z)$  at the interface  $z=0$ .

From these expressions and (4b), the following matrix equation is obtained:

$$\begin{pmatrix} \tilde{G}_{++}(\omega, \alpha) & \tilde{G}_{+-}(\omega, \alpha) \\ \tilde{G}_{-+}(\omega, \alpha) & \tilde{G}_{--}(\omega, \alpha) \end{pmatrix} \cdot \begin{pmatrix} \tilde{E}_+(\alpha) \\ \tilde{E}_-(\alpha) \end{pmatrix} = \begin{pmatrix} \tilde{J}_+(\alpha) \\ \tilde{J}_-(\alpha) \end{pmatrix} \quad (5)$$

where  $\tilde{J}_{\pm}(\alpha)$  are the Hankel transforms of the conductor current densities  $J_{\pm}(r, \theta, z)$  at the interface  $z=0$ .

Expressions for  $\tilde{G}_{++}(\omega, \alpha), \dots, \tilde{G}_{--}(\omega, \alpha)$  are as follows:

$$\begin{aligned} \tilde{G}_{++}(\omega, \alpha) &= \frac{j\omega\epsilon_2}{2\beta_2} \frac{j\beta_2 - \beta_1\epsilon_r \tan(\beta_2 d)}{\beta_1\epsilon_r + j\beta_2 \tan(\beta_2 d)} - \frac{\omega\epsilon_3}{2\beta_3} \\ &\quad - \frac{j\beta_2}{2\omega\mu_2} \frac{\beta_1\mu_r + j\beta_2 \tan(\beta_2 d)}{j\beta_2 - \beta_1\mu_r \tan(\beta_2 d)} - \frac{\beta_3}{2\omega\mu_3} \end{aligned} \quad (6a)$$

and

$$\begin{aligned} \tilde{G}_{+-}(\omega, \beta) &= -\frac{j\omega\epsilon_2}{2\beta_2} \frac{j\beta_2 - \beta_1\epsilon_r \tan(\beta_2 d)}{\beta_1\epsilon_r + j\beta_2 \tan(\beta_2 d)} + \frac{\omega\epsilon_3}{2\beta_3} \\ &\quad - \frac{j\beta_2}{2\omega\mu_2} \frac{\beta_1\mu_r + j\beta_2 \tan(\beta_2 d)}{j\beta_2 - \beta_1\mu_r \tan(\beta_2 d)} - \frac{\beta_3}{2\omega\mu_3} \end{aligned} \quad (6b)$$

$$\tilde{G}_{-+}(\omega, \alpha) = \tilde{G}_{+-}(\omega, \alpha) \quad (6c)$$

$$\tilde{G}_{--}(\omega, \alpha) = \tilde{G}_{++}(\omega, \alpha) \quad (6d)$$

where  $\tilde{G}_{++}(\omega, \alpha), \dots, \tilde{G}_{--}(\omega, \alpha)$  are the admittance Green functions in the Hankel transform domain.

### B. Characteristic Equation

The third step is to derive the characteristic equation. Although the matrix equation (5) contains four unknown functions  $\tilde{E}_{\pm}(\alpha)$  and  $\tilde{J}_{\pm}(\alpha)$ , the functions  $\tilde{J}_{\pm}(\alpha)$  can be eliminated by using Galerkin's method in the Hankel transform domain.

First, we expand unknown  $\tilde{E}_{\pm}(\alpha)$  in terms of known basis functions  $\tilde{E}_{\pm m}(\alpha)$

$$\tilde{E}_+(\alpha) = \sum_{m=1}^M c_m \tilde{E}_{+m}(\alpha) \quad (7a)$$

$$\tilde{E}_-(\alpha) = \sum_{m=1}^M d_m \tilde{E}_{-m}(\alpha) \quad (7b)$$

where  $c_m, d_m$  are unknown constants.

Next, we substitute (7) into (5) and take inner products with  $\tilde{E}_{\pm i}(\alpha)$ . Then the following algebraic equations are obtained:

$$\sum_{m=1}^M K_{im}^{++}(\omega) c_m + \sum_{m=1}^M K_{im}^{+-}(\omega) d_m = 0 \quad (i=1, 2, \dots) \quad (8a)$$

$$\sum_{m=1}^M K_{im}^{-+}(\omega) c_m + \sum_{m=1}^M K_{im}^{--}(\omega) d_m = 0 \quad (i=1, 2, \dots) \quad (8b)$$

where

$$K_{im}^{++}(\omega) = \int_0^\infty \tilde{E}_{+i}(\alpha) \tilde{G}_{++}(\omega, \alpha) \tilde{E}_{+m}(\alpha) \alpha d\alpha \quad (9a)$$

$$K_{im}^{+-}(\omega) = \int_0^\infty \tilde{E}_{+i}(\alpha) \tilde{G}_{+-}(\omega, \alpha) \tilde{E}_{-m}(\alpha) \alpha d\alpha \quad (9b)$$

$$K_{im}^{-+}(\omega) = \int_0^\infty \tilde{E}_{-i}(\alpha) \tilde{G}_{-+}(\omega, \alpha) \tilde{E}_{+m}(\alpha) \alpha d\alpha \quad (9c)$$

$$K_{im}^{--}(\omega) = \int_0^\infty \tilde{E}_{-i}(\alpha) \tilde{G}_{--}(\omega, \alpha) \tilde{E}_{-m}(\alpha) \alpha d\alpha. \quad (9d)$$

In the derivation of (8), Parseval's theorem in the Hankel transform domain is used

$$\begin{aligned} &\int_0^\infty \tilde{E}_{\pm i}(\alpha) \tilde{J}_{\pm}(\alpha) \alpha d\alpha \\ &= \int_0^\infty E_{\pm i}(r, \theta, 0) J_{\pm}(r, \theta, 0) r dr = 0 \quad (i=1, 2, \dots) \end{aligned} \quad (10)$$

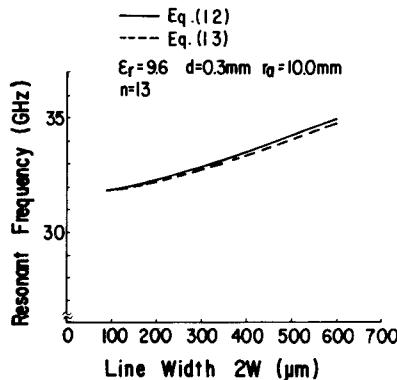


Fig. 2. Resonant frequency of the slot ring resonators for different basis functions as a function of line width.  $n$  is the azimuthal resonant order.

which is valid since the electric field components  $E_{\pm}(r, \theta, 0)$  and the current densities  $J_{\pm}(r, \theta, 0)$  are zero in the complementary regions of the interface at  $z = 0$ .

The following characteristic equation for the complex resonant frequency  $\omega_0$  is obtained by setting zero the determinant of the coefficient matrix  $K(\omega)$ . The resonant frequency is obtained from the real part of this quantity

$$\det |K(\omega_0)| = 0. \quad (11)$$

### C. Basis Functions

As one term approximation using well-behaved basis functions gives good results for infinite slot lines [9], [11], the following basis functions are assumed, that is, the number of the basis functions is only one:

$$E_r(r) = \begin{cases} \frac{1}{2W} \left( 1 + \left| \frac{r - r_m}{W} \right|^3 \right) & \text{(for } |r - r_m| < W) \\ 0 & \text{(for other } r) \end{cases} \quad (12a)$$

$$E_{\theta}(r) = 0 \quad \text{(for all } r). \quad (12b)$$

In the case of a slot line, the characteristic equation reduces to the evaluation of a single integral when the line-length-directed field component is assumed zero. In the case of a slot ring resonator, however, the characteristic equation contains four integrals even if  $E_{\theta}(r) = 0$ .

Hence, in order to investigate the sensitivity of the solution with respect to the basis functions, the following functions are assumed in addition to (12):

$$E_r(r) = \begin{cases} 1 & \text{(for } |r - r_m| < W) \\ 0 & \text{(for other } r) \end{cases} \quad (13a)$$

$$E_{\theta}(r) = 0 \quad \text{(for all } r) \quad (13b)$$

where  $r_m = 1/2(r_a + r_i)$ .

The Hankel transforms of these functions were obtained by numerical integration. The upper and lower integration limits were determined by the limits of the Bessel function's argument in ECL's computer library.

Fig. 2 shows the numerical results of the 13th-order resonant frequencies versus the slot width. As the difference between both results is small, it is considered that the sensitivity of the solution with respect to the basis functions is relatively small. In computation, the solution

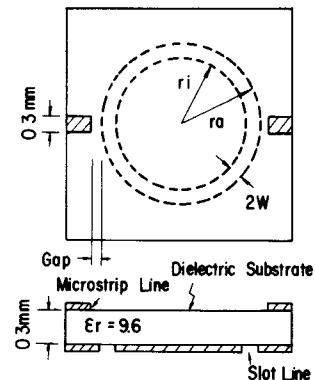


Fig. 3. Experimental geometry for the measurement of a slot ring resonator.

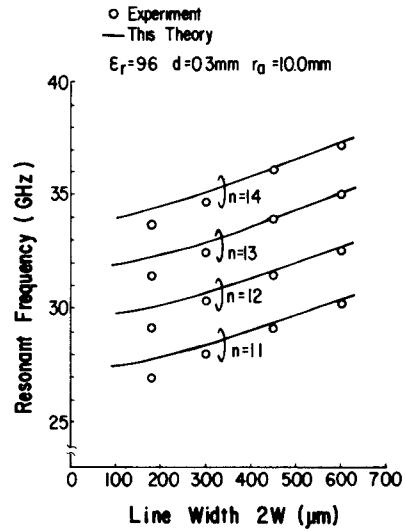


Fig. 4. Theoretical and experimental resonant frequencies for the slot ring resonators as a function of line width.  $n$  is the azimuthal resonant order.

for (11) has been obtained by the method of successive bisection. The integration has been performed in the real axis of the complex  $\alpha$  plane, avoiding the poles of  $\tilde{G}_{++}(\omega, \alpha)$ , etc., the matrix elements  $K_{im}^{++}(\omega, \alpha)$ , etc. A typical computer time is about 20 s on DIPS-M2.

### III. EXPERIMENTAL PROCEDURE

Fig. 3 shows the experimental geometry of a slot ring resonator. Microstrip lines are used for input and output terminals of electromagnetic power on the opposite side of the ring-like slot line. The former is shown as the solid lines and the latter is shown as the dotted lines. The coupling gap between the microstrip lines and the slot line is about 25  $\mu$ m. The substrate is 25  $\times$  25  $\times$  0.3-mm alumina with the relative dielectric constant 9.6. The metals are 0.02  $\mu$ m thick nickel-chromium and 4- $\mu$ m thick gold. The widths of the ring-like slot lines studied are 180, 300, 450, and 600  $\mu$ m. All of them have the same 10-mm outer radius.

### IV. NUMERICAL AND EXPERIMENTAL RESULTS

Fig. 4 shows the resonant frequencies computed from (12) and the measured resonant frequencies. The frequency range investigated is 26–37 GHz which corresponds to about the 10th resonant order. When slot line width in-

creases, the resonant frequency also increases. This means that one wavelength decreases for wider width slot since the outer radius  $r_a$  is constant. The numerical results agree with the experimental results within about 3 percent, especially about 1 percent in the wide linewidth region. It is considered that the sources of the relatively large differences in the narrow line width region are attributed to the basis function. In order to improve the numerical results for this region, more detailed investigation for the basis function is required.  $Q$  values for these resonators are about 500.

## V. CONCLUSION

A numerical method is presented for obtaining the resonant frequencies of open slot ring resonators. The analysis method is based upon Galerkin's method in the Hankel transform domain. The dependence of the solution on the choice of the basis functions is small. The numerical results obtained by this method agree with the experimental results within about 3 percent.

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